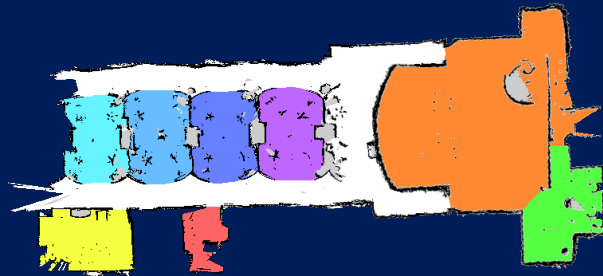




Semantic Web and Robotics: can we work together?



Monitor a large-space
Update the knowledge base
at query time



Instruct a robot to collect outdated
information
Preserve information time-validity

Tiddi, I., Daga, E., Bastianelli, E. and d'Aquin, M. (2016) *Update of time-invalid information in Knowledge Bases through Mobile Agents*, MIRROR-16 workshop at 2016 IEEE/RSJ International Conference on Intelligent Robots and System (IROS 2016)